Autonomous Approach to Small Unknown Bodies

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Program: Topical RTD

Project Objective:

Develop algorithms to onboard estimate the **motion** and **shape** of a small unknown body during approach as well as recover the relative spacecraft trajectory

Benefits to NASA and JPL

A critical capability toward autonomous missions to small bodies, which could provide access to a larger number at more affordable cost. Allows maturing end-to-end autonomy capabilities.



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