

Optical Navigation With Deep Space Optical Communication Terminals

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 Program: Strategic Initiative

Project Objective:

To expand the scope of the currently conceived and developed deep space optical communications (DSOC) transceiver to include on-board astrometry functions to enable autonomous optical navigation (OpNav).

Design Challenge:

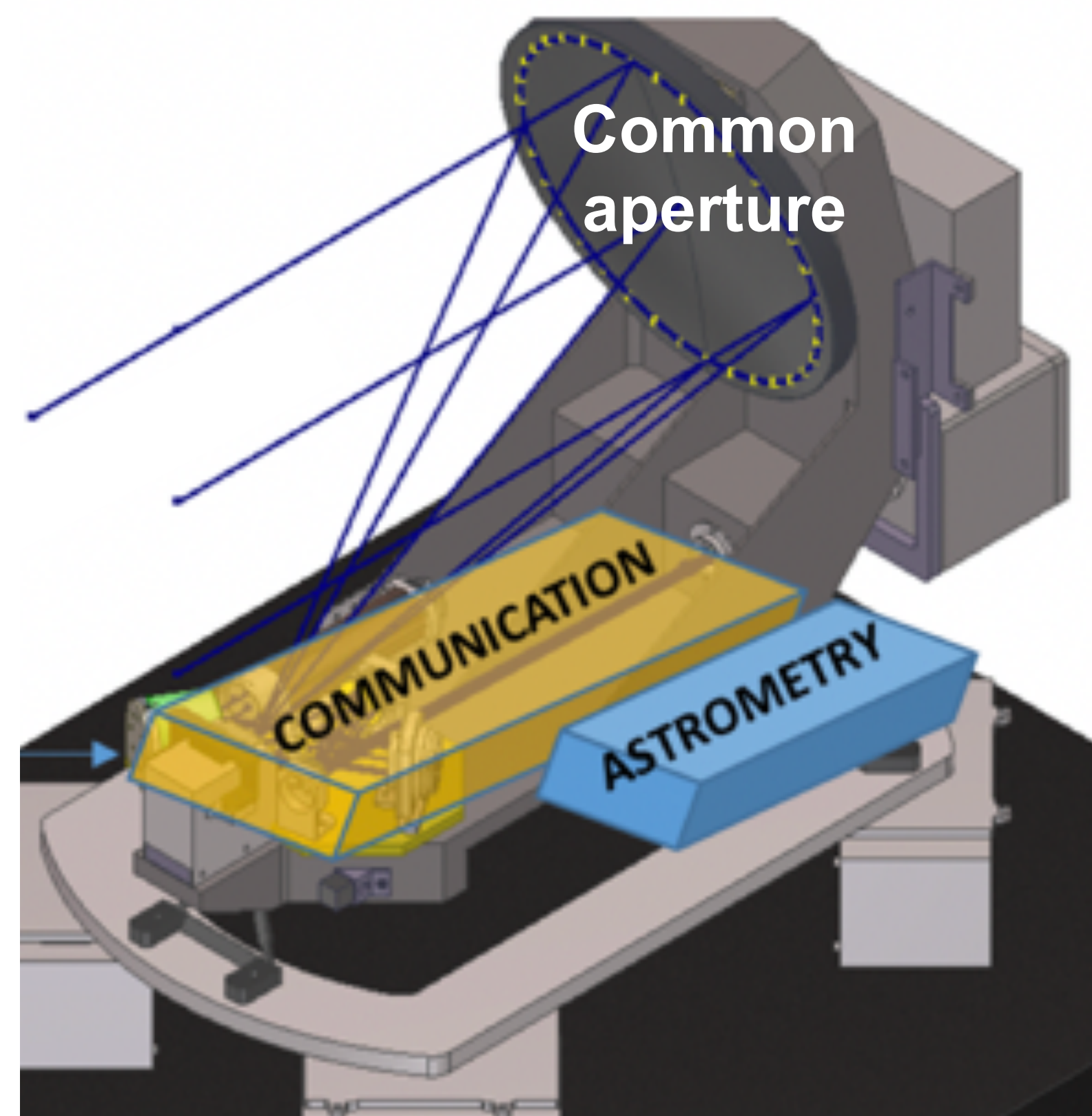
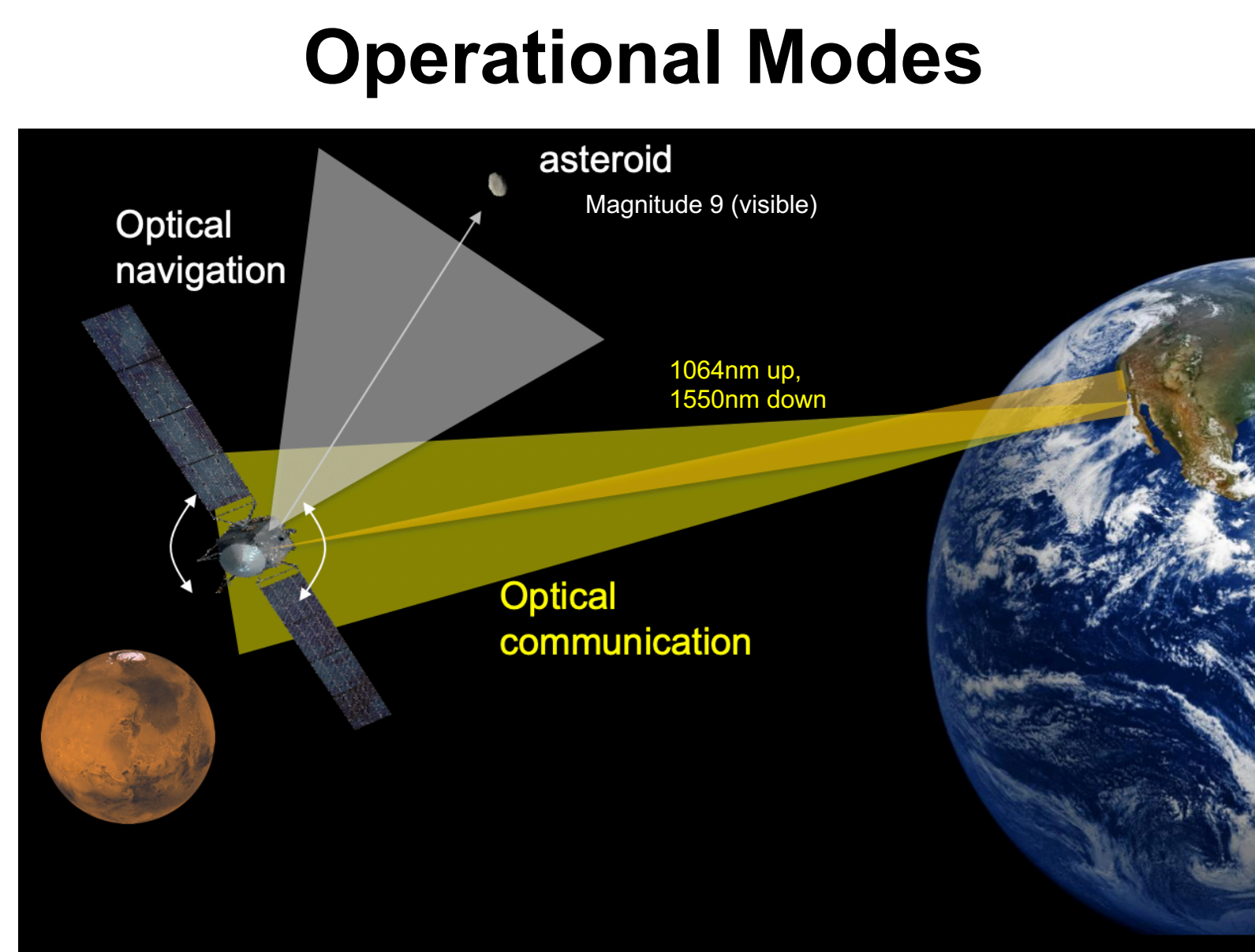
The challenge is to address design deficiencies in current deep space optical transceivers, namely by: (i) providing a large (~10x10 mrad²) field-of-view (FOV) focal plane; (ii) sensors with broadband sensitivity to detect visible Magnitude 9 asteroids with integration times of ~1 second. By contrast, the DSOC optical transceiver under current development has a 256 μrad FOV and uses a photon-counting sensor with very fast temporal response (~ 2 μs) and a spectrally narrow filter with a noise-equivalent bandwidth of 1 nm centered at 1064 nm.

FY18/19 Results: Not applicable; task started in FY20

Base Assumptions:

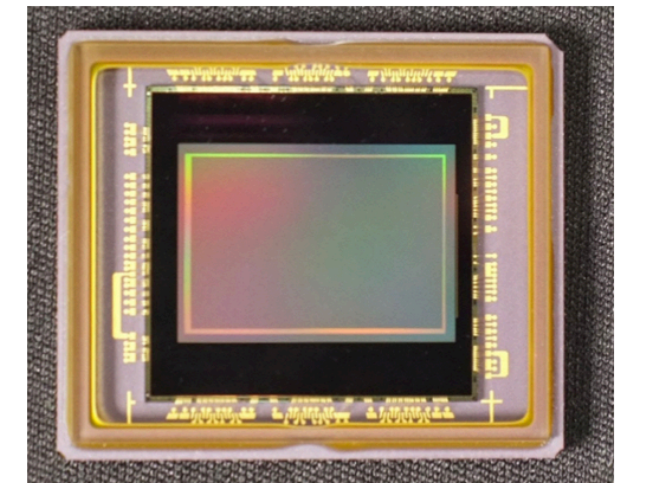
- DSOC performance *cannot* be compromised when adding astrometry
- Uplink acquisition and pointing:** The PCC must accurately detect and track the uplink beacon from Earth as a pointing reference, so that the downlink can be precisely pointed to the ground receiver. Required background mitigation techniques include lock-in detection of the beacon modulation and spectral filtering with a 1-nm bandpass filter. *Adding astrometry cannot degrade the uplink acquisition accuracy.*
 - Stray Light:** Stray light for DSOC is limited with a 1-mrad field stop at the entrance to the aft optics. This is too narrow for OpNav. This work acknowledges the need for a larger field stop (e.g. dichroic field stop with a larger FOV for OpNav), but does not yet have a recommended detailed design. *Adding astrometry cannot increase stray light*

Multi-functional Optical Terminal



Current Detector Technology

DSOC Photon-Counting Camera (PCC) vs Astrometry Camera



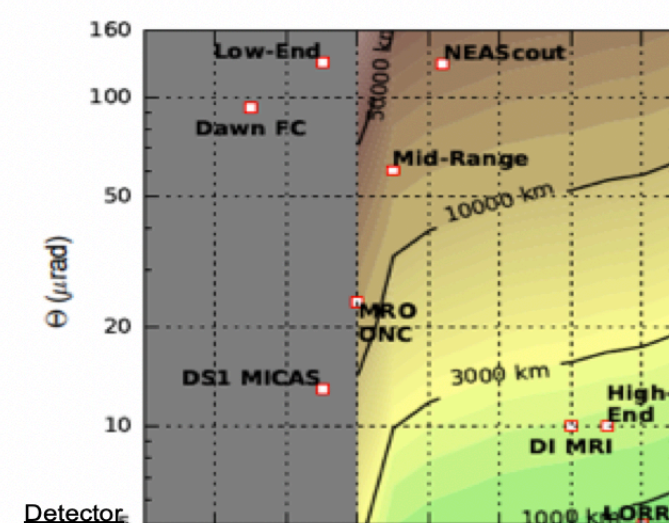
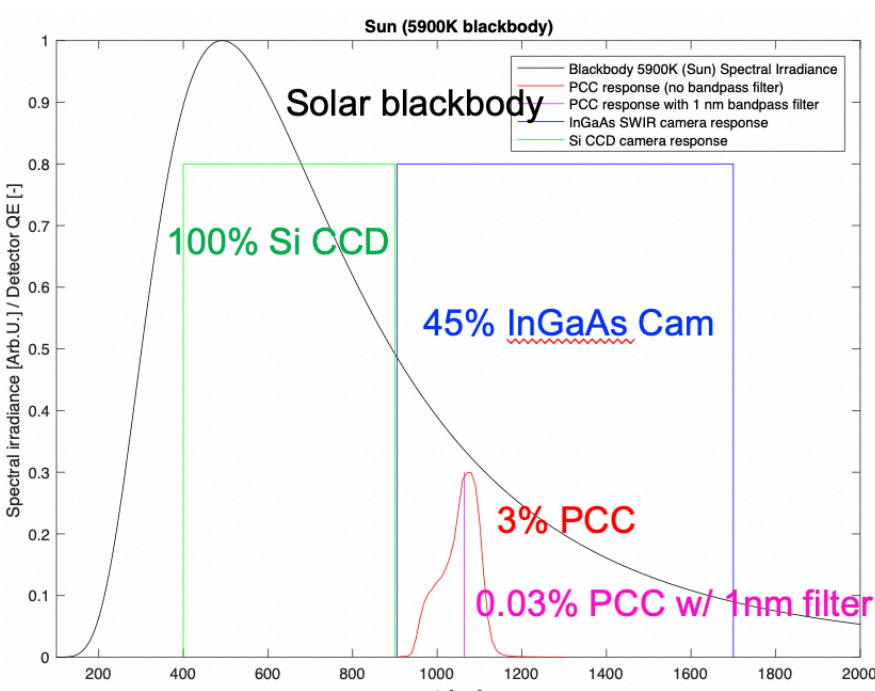
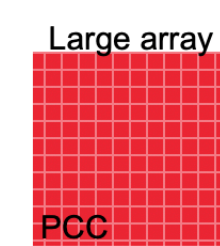
- Focal Plane Array**
 - 32x32 pixel
 - InGaAsP Geiger-Mode APD
 - NIR, 1.3 μm-cutoff, 1-nm bandpass
 - 2us frame rate, 2ns time resolution
 - Complex, timing-sensitive read-out circuit
- Focal Plane Array**
 - 10MegaPixels
 - CCD Array
 - Visible wavelengths, broadband
 - >1s frame rate
 - Simple read-out circuit

Approach and Results:

Considered three options for implementing an on-board astrometry capability for DSOC

Option 1 - Single detector concept

- Use PCC ("as-is" or larger) for OpNav and communication



Detector	Mag 10	11	12	13	14
Si CCD camera	9	10	11	12	13
InGaAs SWIR camera	6	7	8	9	10
PCC (without 1nm filter)	0	1	2	3	4
PCC (with 1nm filter)	0	1	2	3	4

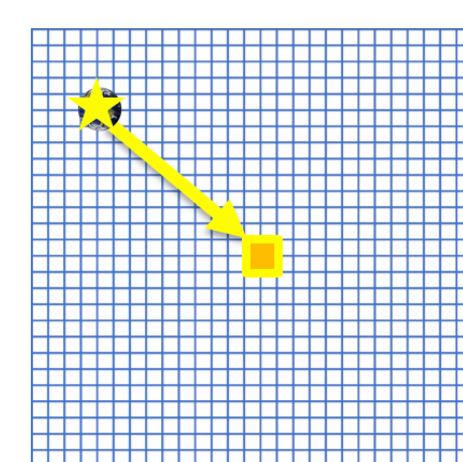
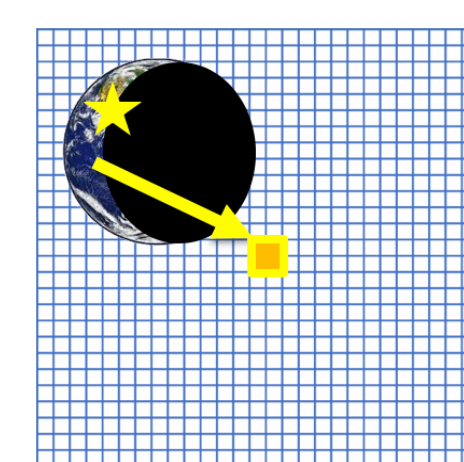
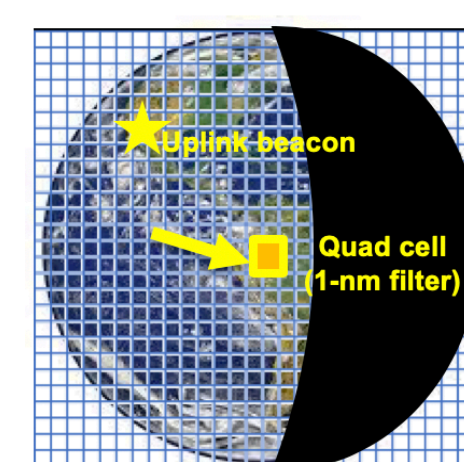
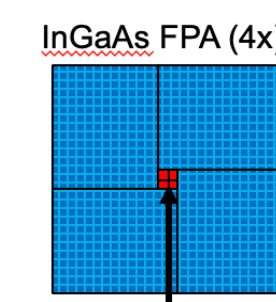
High spectral loss from limited PCC detection bandwidth

Loss increases required object brightness for OpNav

High spectral loss prohibits use of PCC for OpNav. ❌

Option 2 - Hybrid detector concept

- Use InGaAs FPA for astrometry and beacon acquisition
- Use fast PCC quad-cell for tracking and communication
- Assume no 1-nm bandpass filter, except on the quad cell.



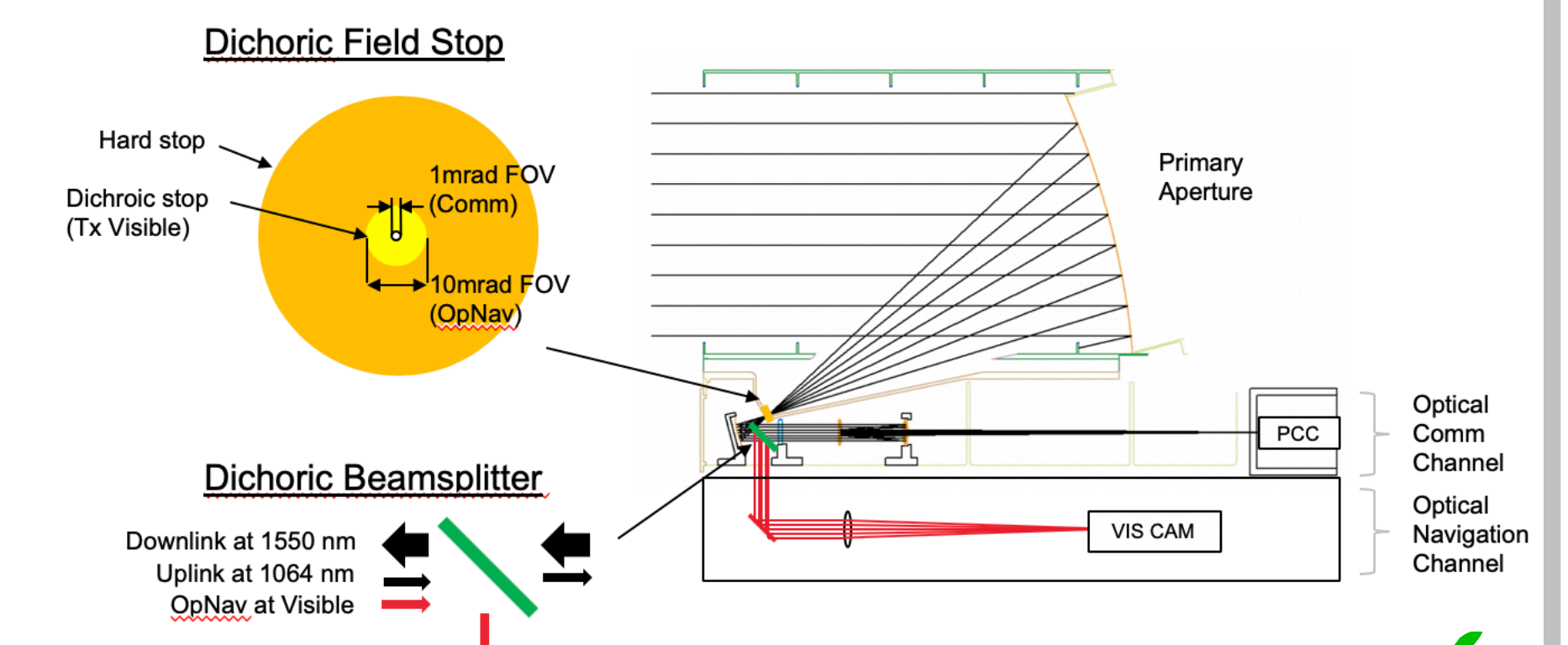
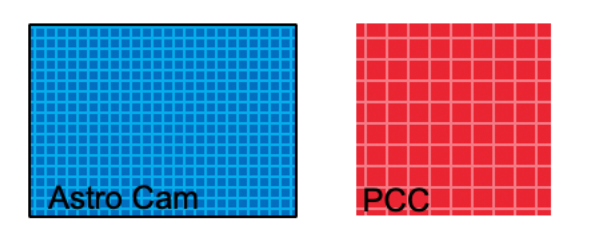
- Earth fills substantial area on FPA
- Centroiding on earth image will not guarantee centroiding on the uplink beacon onto the center quad cell
- Requires step-stare scan pattern for uplink acquisition
- Removal of the 1-nm filter significantly reduces acquisition SNR by >20dB!

- Earth covers a few pixel area, which is small enough to centroid accurately on the 1nm bandpass filter on the center quad can reject the earth illumination and acquire the beacon

Narrowband filter required for uplink acquisition prohibits hybrid detector ❌

Option 3 - Separate detector concept

- Share common primary aperture
- Use separate channels in aft optics



Separate channels to optimize communication and OpNav independently ✅

Benefits to NASA and JPL (or significance of results):

The significance of this R&TD research is that astrometry and communication can be supported in a future DSOC terminal sharing a common large aperture. However, due to opposing design requirements, optical navigation and communication shall be implemented with separate back-end optical channels with dedicated detectors. Optical navigation should be viable for magnitude 9 asteroid targets within the solar system based on preliminary signal-to-noise calculations in this feasibility study. Future work is to proceed with the detailed optical design of the optical navigation channel and develop a compatible concept-of-operations with communications.