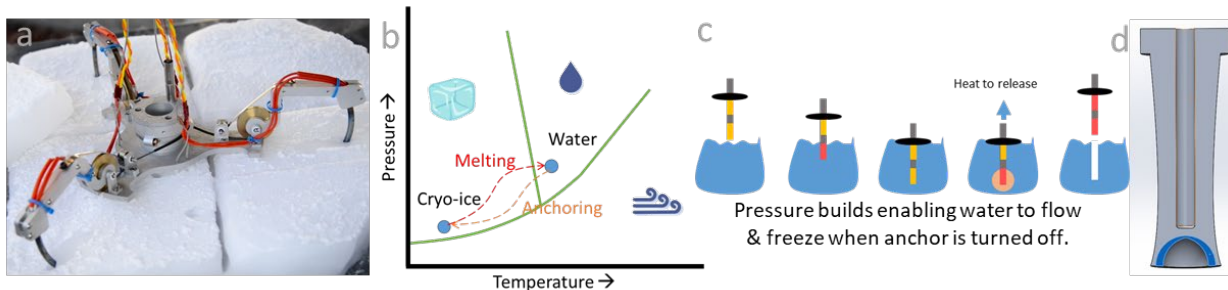


Tutorial Introduction

Abstract

The goal of this task is to improve ice anchoring robustness, reduce power consumption, and mass requirements to a third of current architectures. Current mobility architectures require three points of contact with a large gripping hand to react with all degrees of freedom and ensure a strong foothold. With JPL's recent development of 3d printable locally porous structures, a cryo-ice melt-gripper can provide capillary paths for the liquid water to wick inside of. Once the water refreezes, the anchor will create additional locking moments, allowing a single gripper to react on all six degrees of freedom.



(a) A traditional ice-gripping architecture requiring three points of contact. (b) A representative phase diagram for water showing the anticipate melt/freeze path for the gripper. (c) Schematic of the anchoring/removal process. (d) Concept anchor with solid material colored gray and porous in blue.



Problem Description

- a) Context (Why this problem and why now)
 - a) NASA has identified icy worlds as important locations for future planetary landers
 - b) Icy surfaces pose unique challenges for gripping versus solid rock or dusty terrain
 - c) JPL has created a unique method for creating multifunctional structures with integrated interconnected porosity
- b) SOA (Comparison or advancement over current state-of-the-art)
 - a) Current ice grippers require three points of contact react against all six degrees of freedom (3 translational/3 rotational)
 - b) Traditional ice anchors due not work due to hardness of cryo-ice
 - c) Simple heated anchors would require lots of energy to sublimate ice
 - d) A properly designed ice anchor sunk into cold ice can prevent rotation and translation with a single anchor
- c) Relevance to NASA and JPL (Impact on current or future programs)
 - a) The melt anchor system could enable compact mobility systems useful in a variety of environments
 - a) Climbing narrow crevasses
 - b) Low impact anchoring for low gravity environments such as Enceladus
 - b) Can be integrated with a porous capillary liquid sampling system



Methodology

a) Formulation, theory or experiment description

a) Build an environmental test chamber

- ▶ Low enough pressure to sublimate ice
- ▶ Integrated load cell
- ▶ Contain a movable stage to position ice
- ▶ Move anchor vertically with controllable loading

b) Design a large assortment of ice anchors to optimize for resisting rotation, shear, pullout, and optimize for energy use

b) Innovation, advancement

a) Demonstrate the ability to form liquid water in a cryo-vacuum environment

b) Show single point anchoring to resist shear, rotation, and removal from ice environment

c) Demonstrate low size, weight, and power compared to a traditional gripping system

d) Customizability of anchor design for local environment (climbing ice crevasses, anchoring on a surface, low gravity, porous ice)



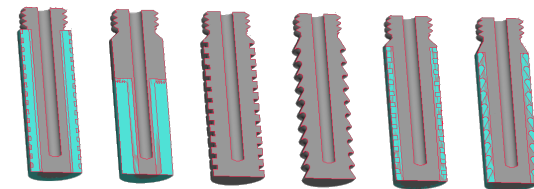
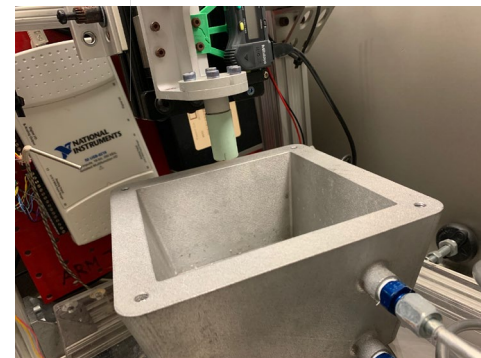
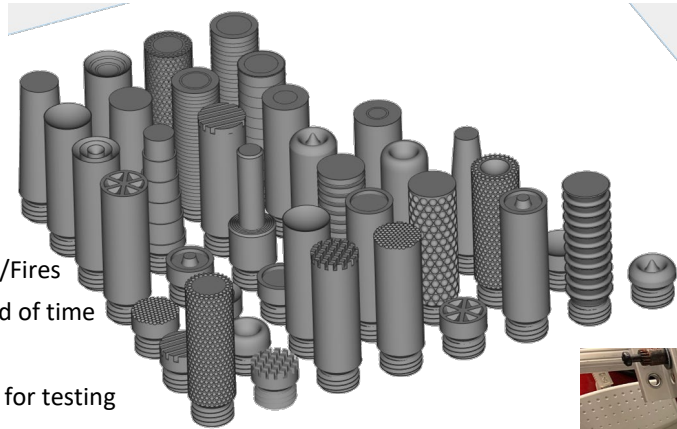
Results

a) Accomplishments versus goals

- a) Significant setbacks in accomplishing tasks due to Covid/Fires
 - a) Difficulty in accessing labs for an extended period of time
 - b) Delays in deliveries of parts
 - c) Unable to get final tray of ice anchors fabricated for testing
- b) Were able to build, prepare, and program test chamber and ancillary equipment
- c) Unable to perform tests due to repeated schedule slips. If funding would continue, could quickly complete the testing forecast for this task.

b) Next steps

- a) Seek bridge funding to complete task
- b) Develop PICASSO proposal for instrument idea developed during project
 - a) Low impact capillary pumping system with integrated low-power instruments.
 - ▶ Liquid conductivity (measuring total dissolved solids)
 - ▶ Particle count
 - ▶ Mechanical strength of ice
 - ▶ Rapid characterization
 - ▶ Concentration of particulates
 - ▶ Thermal properties of ice
 - ▶ Can double as mechanical anchor



Publications and References

None.